Problems for Chapter 5: ODEs

Qu 5.1: Let $\mathbb{Z}_2 = \langle r \rangle$ act on \mathbb{R} by $r \cdot x = -x$. Show that the differential equation $\dot{x} = \sin(2x)$ has symmetry group \mathbb{Z}_2 . Let x(t) be the solution with initial value x(0) = 1, and let u(t) be the solution with initial value u(0) = -1. How are x(t) and u(t) related?

Qu 5.2: Let D_3 be the usual dihedral subgroup of order 6 of O(2), generated by r_0 and $R_{2\pi/3}$. Consider the system of ODEs

$$\begin{cases} \dot{x} = x + x^2 - y^2 \\ \dot{y} = y - 2xy \end{cases}$$

(a) Show this system has D_3 symmetry.

(b) List all three axial subgroups of D_3 . By choosing one of these, find all equilibria of this system with axial symmetry, and explain briefly why it is enough to consider only one of the axial subgroups.

Qu 5.3: Let *L* be an $n \times n$ matrix, and consider the first order ODE $\dot{\mathbf{x}} = L\mathbf{x}$ on \mathbb{R}^n . Show this is equivariant for a linear action of a group *G* if and only if *L* commutes with all the matrices in the representation of *G*.

Qu 5.4: Consider the following family of system of ODEs in the plane

$$\begin{cases} \dot{x} = ax + x^2 - y^2 \\ \dot{y} = ay - 2xy \end{cases}$$

Here $a \in \mathbb{R}$ is a parameter. This is similar to a previous question, and the system has D₃ symmetry. Describe the bifurcations of equilibrium points that occur on the lines of symmetry as *a* is varied through a = 0.

Qu 5.5: Consider the similar system with symmetry D₄:

$$\left\{ \begin{array}{rrr} \dot{x} &=& x+x^3-3xy^2\\ \dot{y} &=& y-3x^2y+y^3. \end{array} \right.$$

(a) Show this system has D₄ symmetry.

(b) List all axial subgroups of D_4 , and find all equilibria of this system with axial symmetry. (Explain briefly why in this case it is *not* enough to consider only one of the axial subgroups.)

Qu 5.6: Check that the two systems in Examples 5.4 have symmetry S_3 and \mathbb{Z}_4 respectively.

Qu 5.7: Consider the following system of ordinary differential equations,

$$\begin{cases} \dot{x} = -x + yz^{2} \\ \dot{y} = -y + xz^{2} \\ \dot{z} = z(1 + xy - z^{2}). \end{cases}$$
(*)

Consider the action of the group $G \simeq \mathbb{Z}_2 \times \mathbb{Z}_2 \times \mathbb{Z}_2$ generated by the matrices

$$A = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \qquad B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \qquad C = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

JM, 27-03-2020

(C) University of Manchester

- (i). Show that the matrices *A*, *B*, *C* do indeed generate a group isomorphic to $\mathbb{Z}_2 \times \mathbb{Z}_2 \times \mathbb{Z}_2$ (you need to show that $A^2 = I$ etc, and *A*, *B*, *C* all commute).
- (ii). Show that the system (*) has symmetry *G*.
- (iii). Deduce that the x-y plane and the z-axis are each invariant under the evolution of the system, stating carefully any results used.
- (iv). Can you find other invariant subspaces?
- (v). Find all the equilibrium points that lie on these subspaces.
- (vi). Find the unique solution to this system with initial value (x, y, z) = (1, 1, 0). What is the limit as $t \to \infty$ of this solution?

Qu 5.8: The octahedral group \mathbb{O}_h is the group of all symmetries of the cube (including reflections). With vertices at the 8 points $(\pm 1, \pm 1, \pm 1)$, it is generated as follows.



Here R_z is a rotation about the *z*-axis by $\pi/2$, R_d is a rotation by $2\pi/3$ about the diagonal x = y = z, and r_z is the reflection in the *x*-*y* plane.

Consider the following family of potential functions in 3-D:

$$V = \lambda \left(x^2 + y^2 + z^2 \right) - 2 \left(x^4 + y^4 + z^4 \right) + 3 \left(x^2 y^2 + z^2 x^2 + z^2 y^2 \right),$$

(this is an approximation to the system of 8 identical springs each attached to the vertex of a cube, and all attached to a common particle).

(i) Show V has symmetry \mathbb{O}_h (it is enough to show it is invariant under the 3 given generators).

(ii) Show that the lines $L_1 = \{(0, 0, z) \mid z \in \mathbb{R}\}$ and $L_2 = \{(x, x, 0) \mid x \in \mathbb{R}\}$, and $L_3 = \{(x, x, x) \mid x \in \mathbb{R}\}$, are all 1-dimensional fixed point spaces, and find the corresponding axial subgroups. [Hint: sketch each of these lines on the figure with the cube.]

(iii) Find critical points (equilibria) occurring in these 1-dimensional fixed-point subspaces, and describe how these appear/disappear as λ varies (i.e., the bifurcations involved).

(iv) Find the other 1-dimensional fixed point spaces (all others are equivalent under the summery group \mathbb{O}_h to L_1, L_2 or L_3), and list the corresponding equilibrium points.